HOW NUTANIX WORKS

The Definitive
Guide to
Hyperconverged
Infrastructure

NUTANIX

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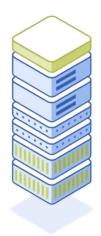
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IT at a Crossroads

IT is increasingly being asked to spend less time on infrastructure and more time (and budget) on application services that add business value. Despite a continuous stream of IT hardware and software enhancements, the infrastructure challenges faced by IT teams continue to rise. The IT infrastructure and virtualization software required to meet the needs of business is complex and expensive, and datacenter management has become painful. Far too much time and effort are focused on just keeping the lights on.

Legacy infrastructure—with separate storage, storage networks, and servers—is not well suited to meet the growing demands of enterprise applications or the fast pace of modern business. The silos created by traditional infrastructure have become a barrier to change and progress, adding complexity to every step, from ordering to deployment to management. New business initiatives require buy-in from multiple teams, and IT needs must be predicted 3-to-5 years in advance. As most IT teams know, this involves a substantial amount of guesswork and is almost impossible to get right. In addition, vendor lock-in and increasing licensing costs are stretching budgets to the breaking point.



- 1. INHERENT COMPLEXITY
- 2. INEFFICIENT SILOS
- 3. FORKLIFT SCALING
- 4. PAINFUL MANAGEMENT

Time for a Different Approach?

Enterprise IT teams today are looking for ways to deliver on-premises IT services with the speed and operational efficiency of public cloud services such as Amazon Web Services (AWS), Microsoft Azure, and Google Cloud.

Taking cues from web giants, hyperconverged infrastructure (HCI) combines common datacenter server hardware using locally attached storage devices (spinning disk or flash) with intelligent software to eliminate common pain points associated with legacy infrastructure.

Nutanix delivers a comprehensive distributed infrastructure platform that bridges the wide gap between traditional infrastructure and public cloud services. The solution delivers turnkey infrastructure that integrates servers, storage, and virtualization along with end-to-end systems management and operations management capabilities. This allows enterprises to deploy infrastructure in minutes and shift the focus to applications that power the business.

What is Hyperconverged Infrastructure?

Hyperconverged infrastructure combines common datacenter hardware using locally attached storage resources with intelligent software to create flexible building blocks that replace legacy infrastructure consisting of separate servers, storage networks, and storage arrays.

Hyperconvergence is the fundamental building block for distributed cloud-like infrastructure. This book gives an overview of the Nutanix hyperconverged solution and walks through how different features and functionality provide a fast, highly scalable, and efficient datacenter solution for enterprises of all sizes.

Figure 1. Challenges of legacy three-tier infrastructure.

The Nutanix Solution

Nutanix converges the entire datacenter stack, including compute, storage, storage networking, and virtualization. Complex and expensive legacy infrastructure is replaced by AOS running on state-of-the-art, industry-standard servers that enable enterprises to start small and scale one node at a time. Each server, also known as a node, includes Intelpowered x86 or IBM Power hardware with flash SSDs and HDDs. Nutanix software running on each server node distributes all operating functions across the cluster for superior performance and resilience.

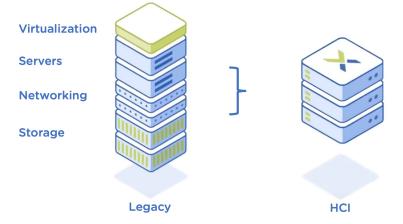


Figure 2. Nutanix converges compute, storage, and virtualization in simple, scalable building blocks.

A single Nutanix cluster can scale as large as the hypervisor cluster it is on. Different hardware platforms are available to address varying workload needs for compute and storage. Nutanix software is hardware agnostic, running on hardware from vendors such as Dell, Lenovo, Cisco UCS, and HPE Prol iant, and from Nutanix as well.

NUTANIX Community Edition and Community Edition On-Demand

<u>Community Edition</u> is a free, 100 percent software solution that lets enterprises easily evaluate the latest Nutanix technology at zero cost on existing hardware or via a Nutanix Test Drive.

Hardware platform configurations are available to fit any workload by independently scaling the various resources (CPU, RAM, or Storage) and can be provisioned with or without GPU for graphics acceleration. All nodes include flash to optimize storage performance, and all-flash nodes are available to deliver maximum I/O throughput with minimum latency for all enterprise applications.

Prism and AOS

Most HCI solutions consist of two fundamental components: a data plane and a management plane.

AOS is a distributed data plane for either VMs or containerbased applications that runs across a cluster of nodes delivering enterprise storage and virtualization services.

Prism is a distributed management plane that uses advanced data analytics and heuristics to simplify and streamline common workflows, eliminating the need for separate management solutions for servers, storage networks, storage, and virtualization. This suite of features enables application and business requirements to be met within the hyperconverged infrastructure, with no need to rely on external services. In other words, you can build a complete datacenter on Nutanix HCI.

How Nutanix Software Is Deployed

A Nutanix cluster is 100 percent software defined. Each node in a cluster runs a hypervisor (VMware ESXi, Microsoft Hyper-V, or the native Nutanix hypervisor, AHV), and the Nutanix software runs as a virtual machine called the Controller VM (CVM) that runs on every node in the cluster. The CVM includes Prism management functions and AOS distributed storage functions.

Nutanix Leads the Pack

Nutanix was named a Leader in the inaugural 2019 Gartner Magic Quadrant for Hyperconverged Infrastructure. Read the report to see why!



The Leading HCI Platform

Nutanix AOS is the distributed infrastructure platform that makes hyperconvergence possible. The main components are:

AOS Distributed Storage

- Enterprise storage services for applications, eliminating the need for separate solutions from vendors such as NetApp, EMC, and HP
- Includes a comprehensive set of capabilities for performance acceleration, data reduction, data protection, and much more
- Full support for VMware® vSphere, Microsoft® Hyper-V, Citrix® Hypervisor, and Nutanix AHV

Nutanix AHV Virtualization

- Comprehensive virtualization solution included with Nutanix at no additional charge
- Hardened to meet the most stringent enterprise security requirements
- Integrated virtual machine management through Prism
- Intelligent virtual machine (VM) placement, live migration, hypervisor conversion, and cross-hypervisor high availability for maximum flexibility

Scale-Out Storage Services

- Nutanix Files file services provides access to Microsoft
 Windows via SMB 2.1 and to Linux and Unix via the NFS v4
 protocol. This solution scales and load balances multiple
 nodes in the cluster, growing capacity and performance as
 needed
- Nutanix Objects is a software-defined object storage solution that non-disruptively scales-out while lowering overall costs. It supports an industry-standard S3compatible REST API to handle petabytes of unstructured data

 Nutanix Volumes™ block services provides iSCSI access to applications that require direct access to block storage. This can be nonvirtualized systems, or virtual machines with specific requirements. Volumes utilizes the DSF to scale I/O across the entire cluster and can load balance and accelerate specified Volume Groups

Advanced Virtual Networking with Nutanix Flow

- Microsegmentation provides a proactive and adaptive approach to VM network security
- Service chains that enable network feature virtualization
- Network visualization and optimization
- · Network automation and orchestration

AOS Distributed Storage

AOS Distributed Storage simplifies storage and data management for virtual environments. By pooling flash and hard disk drive storage across a Nutanix cluster and exporting it as a data store to the virtualization layer as iSCSI, NFS, and SMB shares, DSF eliminates the need for SAN and NAS solutions.

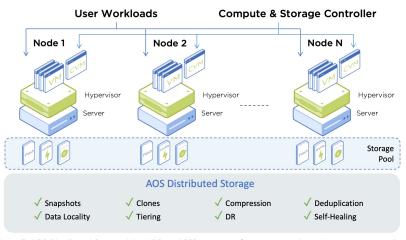


Figure 3. AOS Distributed Storage joins HDD and SSD resources from across a cluster into a storage pool

Infrastructure Resilience

The Nutanix platform is designed to be fault tolerant, with no single points of failure or performance bottlenecks.

Tunable Redundancy

With tunable redundancy, each Nutanix container is configured with a replication factor (RF) of two or three. RF=2 ensures that two copies of data are maintained at all times, allowing the cluster to survive the failure of a single node or drive. When RF is set to 3 (RF=3), three copies of the data are maintained in a cluster, providing resilience against two simultaneous failures. RF=2 is considered the best practice in most scenarios.

Replication Factor Versus RAID

RAID has been a popular way of protecting against drive failures while limiting the extra storage capacity required. Rebuilding a multi-TB drive can take days to complete, creating a risk of data loss should further failures occur. RAID has gone from single to double and even tripleparity to try to reduce this risk.

Nutanix Replication Factor (RF) eliminates reliance on RAID, the need for expensive spare drives that sit idle, and the performance penalty that comes with multiple parity calculations.

Data Path Redudancy

Data path redundancy ensures high availability in the event a Nutanix Controller VM (CVM) becomes unavailable or needs to be brought down for upgrade. If a CVM becomes unavailable for any reason, Nutanix CVM autopathing automatically reroutes requests to a "healthy" CVM on another node. This failover is fully transparent to the hypervisor and applications.

Data path redundancy is possible because every node in a cluster has access to all copies of data—I/O requests can be serviced immediately by any node in the system.

Nutanix Software Upgrades and Data Path Redundancy

Nutanix software upgrades take advantage of reliable data path redundancy. While the local CVM is unavailable because of software upgrade or a failure, VMs running on the node use data path redundancy to satisfy I/O through a CVM on another node—transparent to users and applications.

Integrity Checks

AOS has a variety of features to proactively identify and fix issues related to data consistency and integrity, bit rot failures, and hard disk corruption.

- Detection of silent data corruption and repair of data consistency errors
- Automatic data integrity checks during every read
- Automatic isolation and recovery during drive failures

Availability Domains

Availability domains offer greater protection from hardware failures by allowing Nutanix clusters to survive the failure of a node or block (multinode chassis) or datacenter rack.

Availability domains are created based on the granularity at which failures are likely to occur.

With DSF, data replicas are written to other blocks in the cluster to ensure that in the case of a block failure or planned downtime, the data remains available. This is true for both RF2 and RF3 scenarios, as well as in the case of a block failure. An easy comparison is "node awareness," where a replica would need to be replicated to another node that will provide protection in the case of a node failure. Block and rack awareness further enhance this by providing data availability assurances in the case of block-or rack-level outages.

Performance Acceleration

DSF includes several capabilities that enhance performance:

Intelligent Tiering

DSF continually monitors data access patterns and optimizes data placement on either the SSD or HDD tier, achieving the best performance without administrator intervention.

The SSD tier provides maximum performance for hot data and random I/O, while the HDD tier provides maximum capacity and economy for cold data and sequential I/O.

Data Locality

DSF ensures that as much of a VM's data as possible is stored on the node where the VM is running. This negates the need for read I/O to go through the network. Keeping data local optimizes performance and minimizes network congestion.

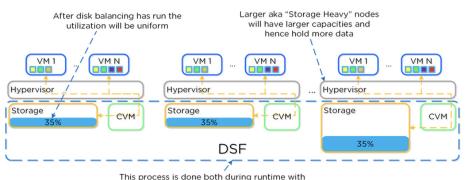
Every VM's data is served locally from the CVM and stored preferentially on local storage. When a VM is moved from one node to another using vMotion or live migration (or during an HA event), the migrated VM's data automatically follows the VM in the background based on read patterns.

Automatic Disk Balancing

Automatic disk balancing ensures that data is distributed uniformly across the entire cluster. Any node in a Nutanix cluster can utilize storage resources across the cluster, without requiring time-consuming and error-prone manual rebalancing.

Automatic disk balancing reacts to changing workloads and allows heterogeneous nodes to be mixed in a single cluster.

Once utilization reaches a set threshold, disk balancing keeps it uniform among nodes.



node/disk placement as well as a background Curator process

Figure 4. VM Flash Mode allows individual ν Disks to be "pinned" in the cluster-wide SSD tier for maximum IOPS and low latency.

Integrated Virtualization

Nutanix AHV is a virtualization solution designed to work perfectly with the entire Nutanix platform, which means there is no need for additional configuration or management to get the best application performance. AHV also includes AHV Turbo, which is a hypervisor I/O enhancement built to take advantage of next generation, ultra-low latency storage devices like NVMe or Intel Optane. With AHV turbo and data locality, the most demanding applications are guaranteed the performance they need.

Shadow Clones

Shadow clones significantly improve performance by caching virtual machine data across a Nutanix cluster. Unique to Nutanix, shadow clones benefit scenarios where there are multiple VMs reading a single source of data, such as deployment servers and repositories. VDI deployments, where many linked clones forward read requests to a central master (such as Citrix MCS Master VM or VMware View replica disks), are an ideal example.

With shadow clones, Nutanix actively monitors vDisk access trends. If there are requests originating from more than two remote Controller VMs (CVMs), as well as the local CVM, and all of the requests are read I/O, the vDisk will be marked as immutable. Once the disk has been marked immutable, the vDisk is then cached locally by each CVM so read operations are now satisfied locally by direct-attached storage resources.



Capacity Optimization

AOS incorporates a wide range of storage optimization technologies that work together to make efficient use of the available capacity in a cluster.

Deduplication

Nutanix offers two types of data deduplication to accelerate application performance and optimize storage capacity. Performance-tier deduplication removes duplicate data in-line with the content cache (SSD and memory) to reduce the footprint of an application's working set. In addition, global post-process MapReduce deduplication reduces repetitive data in the capacity tier to increase the effective storage capacity of a cluster. Both forms of deduplication can be easily configured and managed at virtual machine and vDisk granularity.

When deduplication is enabled, data is fingerprinted on ingest using a SHA-1 hash. Deduplication operations are software-driven and leverage the hardware-assist capabilities of the Intel chipset for the SHA-1 fingerprint generation. Because SHA-1 is a strong hash, deduplication is performed based on a fingerprint match.

Compression

Data can be compressed inline as it is written to the system, or post-process after the data has been written. Inline and post-process compression is intelligently determined based on sequential or random access patterns to enable optimal performance. DSF executes post-process compression as a series of distributed MapReduce jobs.

Pro Tip: Compression

Use inline compression most of the time; it will not impact random write performance. Inline compression pairs perfectly with erasure coding.

EC-X

Nutanix systems include an innovative implementation of erasure coding technology— Nutanix EC-X—that provides resilience and can increase usable capacity by up to 75 percent. EC-X reduces the capacity cost of replication factor (RF) without taking away any of the resilience benefits and with no impact on write performance.

EC-X encodes a strip of data blocks on different nodes and calculates parity. In the event of a disk or node failure, parity is used to calculate any missing data blocks. DSF uses an extent group as the data block, and each data block in a strip must be on a different node and belong to a different vDisk. The number of data and parity blocks in a strip is configured based on the desired number of failures to withstand.



Data Protection

Nutanix offers natively integrated data protection and continuous availability at the VM level. A range of options is available to meet the recovery point objective (RPO) and recovery time objective (RTO) of different applications.

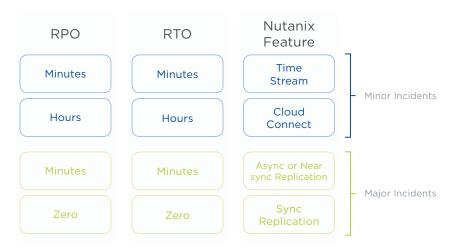


Figure 5. Nutanix data protection options.

What are RTO and RPO?

Recovery Time Objective (RTO) defines how much time you have to recover if an IT failure occurs.

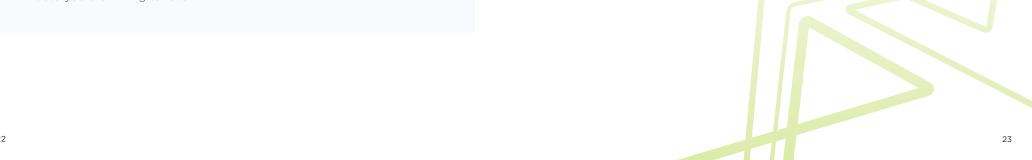
Recovery Point Objective (RPO) defines the maximum amount of data you are willing to lose.

Converged Local Backups with Snapshots

Nutanix can create unlimited metadata-based local snapshots—with VM and application-level consistency—and recover data instantly to meet a wide range of backup and data protection requirements. Metadata based snapshots require minimal disk overhead and ensure high performance recovery.

DSF uses VM-centric snapshots to provide production-level data protection without sacrificing performance. Nutanix utilizes a redirect-on-write algorithm that dramatically improves system efficiency for snapshots.

Many backup vendors combine these capabilities with enterprise storage features from Nutanix. Check our <u>Nutanix Ready program</u> for a list of our backup partners.



Integrated Remote Backup And Disaster Recovery Using Async Replication

Nutanix disaster recovery (DR) and replication capabilities are built on snapshot technology. VM snapshots can be asynchronously replicated or backed up to another datacenter based on a user-defined schedule.

Replication topologies are flexible and bi-directional, enabling one-to-one, one-to-many, and many-to-many deployments. During replication, data is compressed and replicated at the sub-block level for maximum efficiency and lower WAN bandwidth consumption.

Nutanix Prism interface offers a simplified view of all local and remote snapshots, allowing administrators to restore a VM from a snapshot with a single click. In case of disaster, administrators can also failover a VM to the secondary datacenter with a single click.

Self-service File Restore

AOS data protection includes self-service file restore, which allows VM and application owners to recover individual files from VM snapshots without getting an administrator involved.

NearSync

NearSync replication allows for RPOs as low as one minute for protecting your mission-critical applications. By leveraging Nutanix light weight snapshots (LWS), NearSync supports more granular restore capabilities while using the existing DR workflows in Prism. vSphere and AHV support NearSync and there are no latency or distance restrictions.

Metro Availability And Sync Replication

For critical workloads requiring zero RPO, and near-zero RTO, Nutanix offers metro availability, which ensures continuous data availability across separate sites within a metro. With Prism, setting up and managing this feature is simple.

Administrators can set up metro availability bi-directionally between two sites connected over a metro area network. The only network requirement is a round-trip latency of less than five milliseconds. Data is written synchronously to both sites, so it is always available to applications in the event a site fails or needs to undergo maintenance. Virtual machines can be non-disruptively migrated between sites for planned maintenance events or other needs.

We were focused on flexibility and innovation. We were looking for a partner who would be able to understand our business needs. With Nutanix, there was a willingness to listen and propose an innovative solution."

LAURENT PERRIAULT
Director of Operations, Claranet

Security

Nutanix AOS is hardened by default. It utilizes the principle of least privilege, and delivers a true defense-in-depth model. Its custom security baseline exceeds the requirements of the U.S. Department of Defense.

Nutanix combines features such as two-factor authentication and data-at-rest encryption with a security development lifecycle. This is integrated into product development to help meet the most stringent security requirements. Nutanix systems are certified across a broad set of evaluation programs to ensure compliance with the strictest standards.











Figure 6. AOS meets and surpasses some of the most stringent security requirements.

Data-at-rest Encryption

Data-at-rest encryption is delivered through self-encrypting drives (SED) that are factory-installed in Nutanix hardware. This provides strong data protection by encrypting user and application data for FIPS 140-2 Level 2 compliance. For SED drives, key management servers are accessed via an interface using the industry-standard Key Management Interface Protocol (KMIP) instead of storing the keys in the cluster.

Nutanix also provides the option to use a native data-at-rest encryption feature that doesn't require specialized hardware from self-encrypting drives (SED). This feature can optionally leverage a built-in, local key management solution, reducing the complexity of deploying a secured environment.

Two-Factor Authentication

Nutanix solutions support SAML integration and optional two-factor authentication for system administrators in environments requiring additional layers of security. When implemented, administrator logins require a combination of a client certificate and username and password.

Secure Access

Nutanix also offers a higher security configuration option, which restricts access to a Nutanix cluster in security-conscious environments such as government and healthcare datacenters. Cluster lockdown not only disables interactive shell logins automatically but can also enable more restrictive access based on cryptographic keys.

Software Development Lifecycle

Nutanix uses a unique, well-defined Security Development Lifecycle (SecDL) to incorporate security into every step of the software development process, from design and development to testing and hardening. Threat modeling is used to assess and mitigate customer risk from code changes. SecDL testing is fully automated during development, and all security-related code modifications are timed during minor releases to minimize risk.

Secure Configuration Baseline

Nutanix provides a security baseline based on the US DISA STIG format in both human readable format and in eXtensible Configuration Checklist Description Format (XCCDF), which allows automated assessment tools, such as Host Based Security System (HBSS), to read it. This provides detailed information on how to assess a Nutanix system to determine compliance with the baseline requirement, cutting down accreditation time from 9-12 months to a matter of minutes.

Security Automation

A crucial element of security is the ability to track what configurations have changed and return them back to their desired state. AOS uses built-in automation to self-heal any deviation from the security baseline configuration of the platform.



Freedom to Virtualize

Nutanix AOS supports multiple industry standard virtualization solutions, allowing customers to choose the best solutions for their environments, whether on-prem or in the cloud, or both.

This freedom of choice in hypervisors and clouds allows applications and data to move between runtime environments and includes a broad range of capabilities for migrating between different environments, including:

- Non-Nutanix infrastructure to Nutanix systems
- Between Nutanix systems supporting different hypervisor environments
- Nutanix to a public cloud infrastructure

Full-stack Industry-standard Support

Nutanix wields <u>support as a competitive advantage</u> with an industry-leading 90+ Net Promoter Score. Nutanix support covers the entire infrastructure stack—compute, storage, and virtualization.

AOS Distributed Storage underpins data services such as VM-centric provisioning, snapshots, clones, data protection, resilience, and availability for all applications. DSF combines with the following technologies to create enterprise-to-public cloud flexibility.

Foundation: Easily install the hypervisor of your choice as well as AOS software across multiple of clusters at a time even for geographical distributed deployments.

Cross-hypervisor Backup: Backup application data on remote clusters running different hypervisors and recover quickly with a single click.

Xtract: A hypervisor and cloud migration tool. Transfer a running VM to AHV with almost no downtime. Automatically turn the machine off in one hypervisor and on in AHV. Also allows you to automatically move and reinstantiate a VM from one location to another.

AHV

The native Nutanix hypervisor, AHV, provides a much simpler and more scalable virtualization solution by leveraging the software intelligence of the hyperconverged architecture. AHV is so easy to use that it allows enterprises to attend to what adds value--the applications--and liberates virtualization from the domain of specialists—making it easily manageable by anyone, from DevOps teams to DBAs.

AHV is performance-tuned for Nutanix HCI, taking advantage of the intelligent storage services provided by AOS. Because DSF is optimized for use with server virtualization, it provides full data resiliency, and data services such as snapshots, clones, and provisioning operations at VM granularity. As a result, AHV is leaner and focused on delivering secure virtual compute services and high availability.

Karbon

In addition to virtualization, AOS includes an integrated Kubernetes control plane to simplify the deployment and management of cloud-native workloads deployed in containers. Karbon also includes an integrated CSI driver, providing applications deployed in containers with direct access to AOS distributed storage.

When used in conjunction with Nutanix Files and Objects, Karbon enables the development of full stack cloud-native applications that can be deployed anywhere.

Enterprise-Ready Virtualization Solution

Based on Linux KVM/QEMU virtualization, all popular workloads work on AHV, which is hardened to meet the most stringent enterprise security requirements. AHV is included with AOS, so enterprises get full infrastructure and virtualization support from a single vendor with no additional licensing costs.

AHV Data Protection

Each VM running on AHV is automatically protected according to a designated schedule that can include local snapshots as well as replication to a remote site. AHV has full access to all the data protection capabilities of AOS as described above

The Nutanix solution's scale-out architecture enables incremental, predictable scaling of capacity and performance in a Nutanix cluster running any hypervisor, including AHV. Administrators can start with as few as three nodes and scale out without limits. The system automatically discovers new nodes and makes them available for use. Expanding clusters is as simple as selecting the discovered nodes you want to add and providing network configuration details. Through Prism, administrators can image or update new nodes to match the AHV version of their preexisting nodes to allow seamless node integration, no matter what version was originally installed.

AHV Networking

AHV implements common networking functionality and provides a vSwitch that comes configured on each node. The virtual switch connects the Controller VM, hypervisor, and guest VMs to each other and to physical networks. The switch runs on each AHV node and starts automatically with no direct switch-level configuration required before the cluster is operational. Administrators can change the switch configuration to match network resiliency and redundancy needs, based on the customer's environment. AHV also provides IP Address Management natively, removing the complexity of maintaining a separate IPAM system.

Network Virtualization and Security with Flow

Modern networking requirements don't stop with connectivity. Nutanix Flow provides application security, visibility, service insertion, and network automation with partner solutions. Security includes east-west firewalls, or microsegmentation, allowing admins to easily manage network isolation and granular VM- and application-level network policy. The extensive visibility of Flow makes it easier to see the complex interactions of modern applications, while also improving troubleshooting and simplifying policy creation and maintenance. Service insertion and network automation help extend and enhance networking function through partner or API integrations.

Virtual Machine Management

VM management on AHV focuses on creation, updates, deletion, data protection, and monitoring of VMs and their resources. These cluster services and features are all available via the Prism interface, a distributed management layer that is available on the CVM on every AHV host.

VM Operations

Prism displays a list of all VMs in an AHV cluster along with a wealth of configuration, resource usage, and performance details for each VM. Administrators can create VMs and perform numerous operations on selected VMs, including power on or off, power cycle, reset, shutdown, reboot, snapshots and clones, migration, pause, update, delete, and launch a remote console.

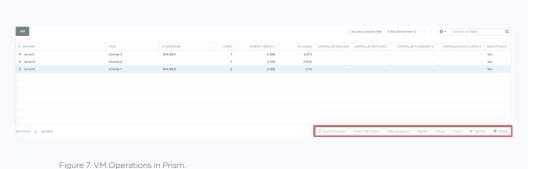


Image Management

The image management service within AHV is a centralized repository that delivers access to virtual media and disk images, as well as the ability to import from external sources. It allows you to store VMs as templates or master images, which you can then use to create new VMs guickly from a known good base image. The image management service can store the virtual disk files that are used to create fully functioning VMs or operating system installation media as an .iso file that you can mount to provide a fresh operating system install experience. Incorporated into Prism, the image service can import and convert existing virtual disk formats, including .raw, .vhd, .vmdk, .vdi and .gcow2. The previous virtual hardware settings do not constrain an imported virtual disk, allowing administrators the flexibility to fully configure CPU. memory, virtual disks, and network settings at the time of VM provisioning.

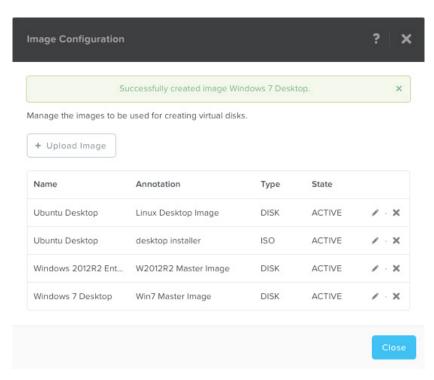


Figure 8. Image Configuration in Prism.

AHV VM Placement And Resource Scheduling

AHV can place virtual machines intelligently on nodes in a cluster based on deep analytics from virtualization, HCI, and networking inputs. Because it's a single stack, intelligent placement or hot spot avoidance decision are all-inclusive.

AOS Dynamic Scheduling

AHV Dynamic Scheduling (ADS) is an automatic function enabled on every AHV cluster to avoid hot spots within cluster nodes. ADS continually monitors CPU, memory, and storage data points to make migration and initial placement decisions for VMs and volumes. Starting with existing statistical data for the cluster, ADS watches for anomalies, honors affinity controls, and makes move decisions to avoid hot spots. Using machine learning, ADS can adjust move thresholds over time from their initial fixed values to achieve the greatest efficiency without sacrificing performance.

Affinity and Antiaffinity

Affinity controls provide the ability to govern where VMs run. AHV has two types of affinity controls: VM-host affinity and Antiaffinity.

VM-host affinity ties a VM to a host or group of hosts, so the VM only runs on that host or group. Affinity is particularly applicable for use cases that involve software licensing or VM appliances. In such cases, you often need to bind a VM appliance to a single host or limit the number of hosts an application can run on.

Antiaffinity lets you designate VMs that should not run on the same hosts. Antiaffinity gives you a mechanism that allows clustered VMs or VMs that are running a distributed application to run on different hosts, thereby increasing the application's

availability and resiliency. The system overrides this type of rule when a cluster becomes constrained, prioritizing VM availability over VM separation.

Live Migration

Live migration allows the system to move VMs from one AOS host to another while the VM is powered on, whether the movement is initiated manually or through an automatic process. Live migration can also occur when a host is placed in maintenance mode, which evacuates all VMs.

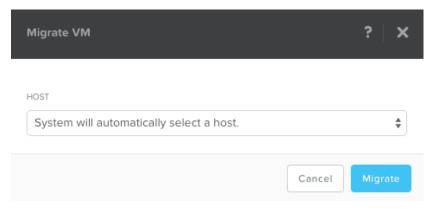


Figure 9. Migrating VMs.

Cross-Hypervisor Migration

Nutanix DSF simplifies the process of migrating existing VMs between an ESXi cluster and an AHV cluster using built-in data protection capabilities. You can create one or more protection domains on the source cluster and set the AHV cluster as the target remote cluster. Then, snapshot VMs on the source ESXi cluster and replicate them to the AHV cluster, where you can restore them and bring them online as AHV VMs.

Automated High Availability

AOS offers virtual machine high availability (HA) to ensure VM availability in the event of a host or block outage. If a host fails, the VMs previously running on that host restart on healthy nodes throughout the cluster. There are multiple HA configuration options available to account for different cluster scenarios.

By default, all AOS clusters provide best effort HA, even when the cluster is not configured for HA. Best effort HA works without reserving any resources. Admission control is not enforced, so there may not be sufficient capacity available to start all the VMs from the failed host.

You can also configure an AOS cluster for HA with resource reservation to guarantee that the resources required to restart VMs are always available. AOS offers two modes of resource reservation: host reservations and segment reservations. Clusters with uniform host configurations (for example, RAM on each node) use host reservation, while clusters with heterogeneous configurations use segment reservation.

High Availability Out-of-the-Box

AHV delivers high availability with minimal configuration and no additional software purchase. When a node fails, VMs are automatically restarted on other nodes in the cluster.

Converged Backup and Disaster Recovery

The AOS converged backup and disaster recovery services protect your clusters. Nutanix clusters running any hypervisor have access to these features, which safeguard VMs both locally and remotely for use cases ranging from basic file protection to recovery from a complete site outage. To learn more about the built-in backup and disaster recovery capabilities in the Nutanix platform, read the Data Protection and Disaster Recovery technical note.

Backup APIs

To complement the integrated backup that the AOS provides, AHV also publishes a rich set of APIs to support external backup vendors. The AHV backup APIs utilize changed region tracking to allow backup vendors to back up only the data that has changed since the last backup job for each individual VM. Changed region tracking also allows backup jobs to skip reading zeros, further reducing backup times and bandwidth consumed.

Nutanix backup APIs allow backup vendors that build integration to perform full, incremental, and differential backups. Changed region tracking is always on in AHV clusters and does not require you to enable it on each VM. Backups can be either crash-consistent or application-consistent.

Analytics

Nutanix Prism offers in-depth analytics for every element in the infrastructure stack, including hardware, storage, and VMs. Administrators can use Element views to monitor these infrastructure stack components, and they can use the Analysis view to get an integrated assessment of cluster resources or to drill down to specific metrics on a given element.

Prism makes detailed VM data available, grouping it into the following categories:

- VM Performance: Multiple charts with CPU and storage-based reports around resource usage and performance.
- Virtual Disks: In-depth data points that focus on I/O types, I/O metrics, read source, cache hits, working set size, and latency on a per-virtual disk level.
- VM NICs: vNIC configuration summary for a VM.
- VM Snapshots: A list of all snapshots for a VM with the ability to clone or restore from the snapshot or to delete the snapshot.
- VM Tasks: A time-based list of all operational actions performed against the selected VM. Details include task summary, percent complete, start time, duration, and status.
- Console: Administrators can open a pop-up console session or an inline console session for a VM.

Figure 11. Performance Summary in Prism.

The Prism Analysis tab gives administrators the tools they need to quickly understand what is going on in their clusters and to identify steps for remediation. You can create custom interactive charts using hundreds of metrics available for elements (such as hosts, disks, storage pools, containers, VMs, protection domains, remote sites, replication links, clusters, and virtual disks) then correlate trends in the charts with alerts and events in the system. You can also choose specific metrics and elements and set a desired time frame when building reports, so you can focus precisely on the data that you're looking for.



Figure 12. Prism Analysis.

Performance

The Nutanix platform optimizes performance at both the distributed storage and hypervisor levels. The CVMs that represent the control and data planes contain the AOS optimizations that benefit all supported hypervisors. Built upon a foundation of open source KVM, a significant amount of added innovation makes AHV uniquely a Nutanix offering. The following sections outline a few of the innovations in AHV that are focused on performance.

AHV Turbo

AHV Turbo yields immediate out-of-the-box benefits for the data path, without any configuration.

AHV Turbo provides a new I/O path that bypasses virtualized storage emulation and directly services storage I/O requests. This approach lowers CPU usage and increases the amount of storage I/O available to VMs. AHV Turbo also introduces a multiqueue approach to allow data to flow from a VM to storage, resulting in vastly higher I/O capacity. The storage queues scale out automatically to match the number of vCPUs configured for a given VM, thus making even higher performance possible as the workload scales up.

While these improvements demonstrate immediate benefits, they also prepare AHV for future technologies such as NVMe and persistent memory advances that offer dramatically increased I/O capabilities with lower latencies.

VNUMA

Modern Intel server architectures assign memory banks to specific CPU sockets. In this design, one of the memory banks in a server is local to each CPU, so you see the highest level of performance when accessing memory locally, as opposed to accessing it remotely from a different memory bank. Each CPU and memory pair is a NUMA node. vNUMA is a function that allows a VM's architecture to mirror the NUMA architecture of the underlying physical host. vNUMA is not applicable to most workloads, but it can be very beneficial to very large VMs that are configured with more vCPUs than there are available physical cores in a single CPU socket.

RDMA

Remote Direct Memory Access (RDMA) allows a node to write to the memory of a remote node by allowing a VM running in the user space to directly access a NIC. This approach avoids TCP and kernel overhead, resulting in CPU savings and performance gains. At this time, AOS RDMA support is reserved for inter-CVM communications and utilizes the standard RDMA over Converged Ethernet (RoCEv2) protocol on systems configured with RoCE-capable NICs connected to properly configured switches with datacenter bridging (DCB) support.

RDMA support, data locality, and AHV Turbo are not only important performance innovations for current generations, but uniquely position AHV and the Nutanix platform to take full advantage of rapidly advancing flash and memory technologies without requiring network fabric upgrades.

GPU Support

A graphics processing unit (GPU) is the hardware or software that displays graphical content to end users. In laptops and desktops, GPUs are either a physical card or built directly into the CPU hardware, while GPU functions in the virtualized world have historically been software-driven and consumed additional CPU cycles. With modern operating systems and applications as well as 3-D tools, more and more organizations find themselves needing hardware GPUs in the virtualized world. You can install physical GPU cards into qualified hosts and present them to guest VMs via passthrough or vGPU mode.

Distributed Management with Nutanix Prism

Nutanix Prism provides an easy way to manage Nutanix environments end to end. Prism combines multiple aspects of HCI management into a single consumer-grade product that lets IT admins manage infrastructure and virtualization, access operational insights, and fix problems, all with a few clicks.

Just as AOS creates a data plane that spans the entire cluster for performance and resiliency, Nutanix Prism creates the same resiliency for management and operational intelligence. Prism comprised two components: Prism Element at the cluster level and Prism Central for multi-cluster management and analytics.

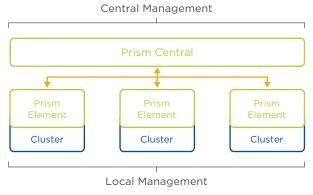


Figure 13. Prism Central.

Prism is Highly Available by Design

Because Prism Element runs on every node in a cluster, it automatically deploys Prism Central as a highly available multi-VM distributed system. There are no external servers or databases to configure.

In addition to the device-friendly HTML5 Prism interfaces, all management capabilities are exposed through comprehensive APIs, PowerShell, and the command line interface (CLI) to facilitate integration and automation.

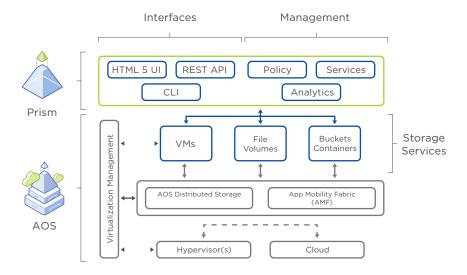


Figure 14. High-Level Prism Architecture.

The Prism Approach

Prism offers an uncluttered experience with an intuitive user interface that simplifies and streamlines common HCI workflows, eliminating the need for different management tools for different tasks. Prism enhances productivity through features such as:

- **Instant Search:** Integrated search to query and perform actions quickly.
- Capacity Planning: Prism's analysis engine forecasts the
 capacity needs of applications running and allows for detailed
 "what if?" impact analysis on a Nutanix cluster, giving the IT
 team the ability to proactively plan for infrastructure needs.
- Predictive Analytics: Leveraging the rich data sources from the HCI and virtualization stack, Nutanix Xfit machine learning provides predictive analysis and insights into resource utilization and resource demand.

- Customizable Operations Dashboard: Visual dashboard gives an at-a-glance summary of application and infrastructure state.
- One-Click Simplicity for infrastructure management, operational insights, and rapid problem remediation.

The Prism UI is a single comprehensive interface for monitoring and control over all the capabilities provided by Nutanix. There are no additional management VMs or plugins required to take advantage of the full breadth of Nutanix AOS functionality, which goes well beyond basic HCI management.

Starting with high-level dashboards for access to the most important statistics and alerts at-a-glance, Prism lets you drill down into HCl infrastructures (servers, drives, networking), multi-hypervisor VM management (create, update, consoles), system health, data protection and replication, deep analytics, and alerting and alarming—all from one management plane.

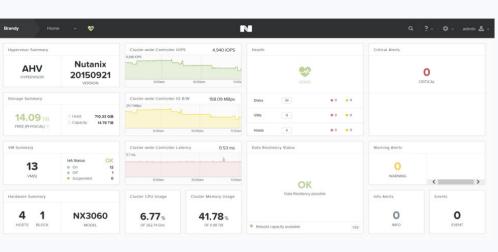
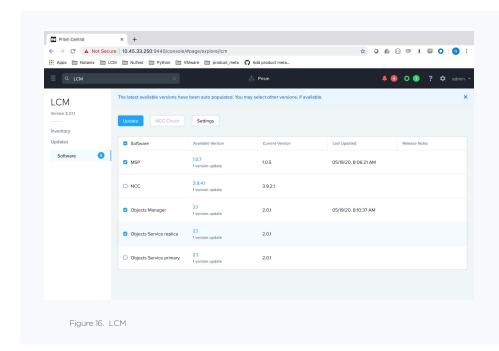


Figure 15. Prism Element — Dashboard.

Lifecycle Manager (LCM)

Prism provides a single interface for managing the software lifecycle of the entire platform, from HCI infrastructure (AOS, Prism, hypervisor) to firmware and BIOS for the underlying hardware..Performing system software upgrades is a simple and non-disruptive process that can occur in the middle of a work day, without the need for careful planning or complicated workflows. LCM automatically maps dependencies and validates compatibility, and then orchestrates the patching and upgrade process without the need for manual intervention.



To conduct an upgrade, just select "LCM" from the Prism menu and select the desired software version from the cloud. Prism automatically maps dependencies and orchestrates the software installation across all nodes. That's it, regardless of cluster size.

Pro Tip: Prism Central

Nutanix recommends Prism Central for larger or distributed deployments (more than one Nutanix cluster or multiple sites) to simplify operations and provide a single management UI across all clusters and sites.

With the Prism Central dashboard, administrators can monitor and manage multiple clusters, including consolidated alerts, available storage, performance (bandwidth and IOPS), and more.

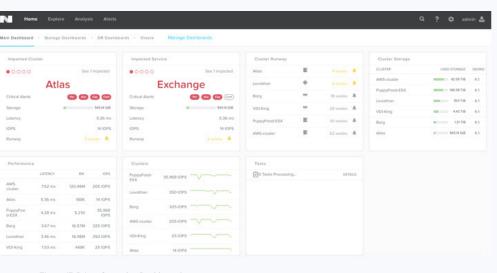


Figure 17. Prism Central — Dashboard.

Organizations can now fully automate hybrid cloud architecture deployments, scaling both multitiered and distributed applications across different cloud environments, including Amazon Web Services (AWS) and Google Cloud Platform (GCP).

Ready to learn more about hyperconverged infrastructure and Nutanix AOS? Contact us at info@nutanix.com, follow us on Twitter @nutanix, or send us a request at www.nutanix.com/demo to set up your own customized briefing and demonstration to see how validated and certified solutions from Nutanix can help your organization make the most of its enterprise applications.

Stay engaged with Nutanix experts and customers on the Nutanix Next online community (<u>next.nutanix.com</u>).

Take a Test Drive

Want to take HCI for a spin? Sign up for a <u>Test Drive</u> and get access to a dedicated AOS environment hosted in the cloud. Sign up is fully automated and only takes a minute.

About Nutanix

Nutanix makes infrastructure invisible, elevating IT to focus on the applications and services that power their business. Nutanix AOS leverages web-scale engineering and consumer-grade design to natively converge compute, virtualization and storage into a resilient, software-defined solution with rich machine intelligence. The result is predictable performance, cloud-like infrastructure consumption, robust security, and seamless application mobility for a broad range of enterprise applications.



